Trees

Binary Search Trees

- **Trees** are one of the **fundamental data structure**.
- Combines the advantage of array and a linked list.
- They are called that, because if you try to visualize the structure, it kind of looks like a tree (root, branches, and leafs).
- Trees are node based data structures, meaning that they're made out of small parts called nodes.
 - Tree Nodes have two or more child nodes.
 - Nodes are connected by edges.



Recursive structures

Sub-trees are disjoint. That is they don't share any nodes. In other word, there is a unique path from the root of a tree to any other node of the tree. This means that every node (except the root) has a unique parent.

- In computer programs, nodes often represent such entities as people, car, airline reservations, and so on.
- In an OOP language like Java these real-word entities are represented by objects.
- The lines (edges) between the nodes represent the way the nodes are related.

Binary Trees

- Each node is capable of two children.
- Represent an important technique for handling structures such as files and directories, dictionaries, and symbol tables.
- If every node in a tree can have at most two children, the tree is called a binary tree. The two children of each node in a binary tree are called the left child and the right child. A node in binary tree doesn't necessarily have the maximum of two children; it may have only a left child, or on a right child, or it can have no children at all.

- Binary tree is a dynamic data structure, that is memory for its nodes is allocated and deallocated during program execution.
- Maximum number of node at any level n is 2ⁿ
- The maximum number of level in n number of node tree is n.
- The minimum number of level in n number of node tree is log (n).

Binary Search Tree(BST)

- To support **O** (log n) search, we add a property to binary tree:
 - **Smaller** and **equal** value to **left**, and **greater** values to **right**.
- In this case BST has the benefits of both sorted array and linked lists.
- BSTs are suitable for applications in which search time must be minimized or in which the nodes are not necessarily processed in sequential order.
- Tradeoff: BSTs with its extra reference in each node, takes up more memory space than a single linked list. In addition, the algorithms for manipulating the tree are somewhat more complicated.
- In its **worst case** if the elements were inserted in order from smallest to largest or vice versa, the tree won't really be a a tree at all, it would be a **linear list**. This called **degenerate tree**.

Search (cont.)



Insertion of an element with key 78:



Balancing a BST

- **O** (log n) \rightarrow if tree is balanced.
- In worst case O (n).
- Full binary tree → a binary tree in which all of the leaves are on the same level and every non-leaf node has 2 children.
 - **Complete binary tree** : a binary tree that is **either full** or full through the **next-to-last level** with the leaves on the last level as far to the left as possible.

Tree terminology

- **Path**: Sequence of nodes.
- **Root**: The node at the top of the tree is called the root. There is only one root in a tree.
 - **Parent**: the node above it is called the parent of the node.
 - Child: The nodes below a given node are called its children.
 - Leaf: a node that has no children is called a leaf node or simply a leaf.
 - **Sub-tree**: Any node may be considered to be the root of a sub-tree, which consists of its children and children's children, and so on.
 - **Visiting**: A node is visited when program control arrives at the node, usually for the purpose of carrying out some operation on the node, such as checking the value of one of its data fields or display it.

- **Traversing**: To traverse a tree means to visit all the nodes in some specified order. For example, you might visit all the nodes in order of ascending key value.
- **Levels**: The level of a particular node refers to **how many generations** the node is from the root.
- **Keys**: One **data field** in an object is usually designated a key value. This value is used to **search** for the item or perform other operation on it.
- Unbalanced Trees: Some of the trees you generate are unbalanced; that is, they have most of their nodes on one side of the root or the other.

5 August, 2010 Un-balanced Binary Search Tree Binary Search Trees



Representing the Tree in Java code:

There are several approaches to representing a tree in the computer's memory. The most common is to store the nodes at unrelated locations in memory, and connect them using references in each node that point to its children.

The node class:

 First, we need a class of node object. These objects contain the data representing the objects being stored and also references to each of the node's two children.

class element

int idno; String stname; element leftchild; element rightchild;

}

There is another way to define node:

class element

student st1; element leftchild; element rightchild;

class student

int idno; String stname;

{

}

{

Java code for Inserting a Node

```
public void insert(int id, String name)
```

```
element newstudent = new element ();
newstudent.idno= id;
newstudent.stname = name;
if(root == null)
  root = newstudent;
else
   element current = root;
   element parent;
  while(true)
     parent = current;
     if(id < current.idno)
       current = current.leftChild;
```

```
parent.leftChild = newstudent;
     return;
else
  current - current.rightChild;
  if(current == null)
     parent.rightChild = newstudent;
     return;
```

Java code for finding a Node

Binary Search Trees

public element find(int key)

```
element current = root;
while(current.idno != key)
{
    if(key < current.idno)
        current = current.leftChild;
    else
        current = current.rightChild;
    if(current == null)
        return null;
}
return current;</pre>
```

Data Structures and Algorithms

Deleting an Item from a BST

- Most complicated common operation required for binary search trees.
- Start by finding the node you want to delete. When you have found the node, there are three cases to consider:
 - □ The node to be deleted is a leaf (has no children).
 - The node to be deleted has one child.
 - □ The node to be deleted has two children.
- The first case is easy. You simply change the appropriate child field in the node's parent to point to null.
 By: Sayed Hassan Adelyar

- The second case isn't so bad either. The node has only two connections: to its parent & to its only child. You have to connect its parent directly to its child.
- If the deleted node hade **two children**, you can't just replace it with one of these children, at least if the child has its own children. To delete a node with two children, **replace** the node with its **in-order successor**.

Binary Search Trees public boolean delete(int key)

element current = root; element parent = root; boolean isleftChild = true;

Data Structures and Algorithms

Binary Search Trees while(current.idno != key)

```
parent = current;
if(key < current.idno)
  isleftChild = true;
  current = current.leftChild;
else
  isleftChild = false;
  current = current.rightChild;
if(current == null)
  return false;
```

```
if(current.leftChild == null && current.rightChild == null)
```

```
if(current == root)
    root = null;
    else if(isleftChild)
        parent.leftChild = null;
    else
        parent.rightChild = null;
}
else if(current.rightChild == null)
    if(current == root)
    root = current.leftChild;
    else if(isleftChild)
        parent.leftChild = current.leftChild;
    else
        parent.rightChild = current.leftChild;
```

```
else if(current.leftChild == null)
        if(current == root)
          root = current.rightChild;
        else if(isleftChild)
          parent.leftChild = current.rightChild;
        else
          parent.rightChild = current.rightChild;
     else
element successor = getSuccessor(current);
     if(current == root)
        root = successor;
     else if(isleftChild)
        parent.leftChild = successor;
     else
        parent.rightChild = successor;
     successor.leftChild = current.leftChild;
  return true;
```

private element getSuccessor(element delelement) {
 element successorParent = delelement;
 element successor = delelement;
 element current = delelement.rightChild;
 while(current !=null) {
 successorParent = successor;
 successor = current;
 current = current.leftChild;
}

```
if(successor != delelement.rightChild) {
    successorParent.leftChild = successor.rightChild;
    successor.rightChild = delelement.rightChild;
```

```
return successor;
```

Finding maximum and minimum values

Binary Search Trees Pubic element maximum()

```
node current, last;
current = root;
while (current !=null)
{
    last = current;
    current = current.rightchild;
}
```

return last;

Finding maximum and minimum values

Binary Search Trees Pubic element minimum()

Data Structures and Algorithms

element current, last; current = root; while (current !=null) { last = current; current = current.leftchild;

return last;

Java code for displaying Tree

Binary Search Trees

public void displayTree()

stack globalStack = new stack(25); globalStack.push(root); int nBlanks = 32; boolean isRowEmpty = false; System.out.println("....."); while(isRowEmpty == false) { stack localStack = new stack(25);

```
stack localStack = new stack(25);
isRowEmpty = true;
for(int j=0; j<nBlanks; j++)
    System.out.print(" ");
```

}

while(globalStack.isempty() == false) {

```
treeitem temp = globalStack.pop();
```

if(temp != null) {

System.out.print(temp.idno);

localStack.push(temp.leftchild);

localStack.push(temp.rightchild);

if(temp.leftchild != null || temp.rightchild != null)

isRowEmpty = false;

```
Data Structures and Algorithms
```

}

else {

System.out.print("....."); localStack.push(null); localStack.push(null); } for(int j=0; j<nBlanks*2-2;j++) System.out.print(" "); } System.out.println(); nBlanks /= 2; while(localStack.isempty() == false) globalStack.push(localStack.pop());

```
System.out.println(".....")
```

Traversing the Tree:

- Traversing a tree means **visiting each node** in a specified order. There are **three simple ways** to traverse a tree:
- Preorder,
- Inorder,
- Postorder,
- The simplest way to carry out a traversal is the use of **recursion**.

Binary Search Trees In-order Traversal:

- Tree Nodes have two or more child nodes; unlike our list node, which only had one child.
 - An in-order traversal of a binary search tree will cause all the nodes to be visited in **ascending order** based on their key values. If you want to create a sorted list of the data in a binary tree, this is one way to do it. The simplest way to carry out a traversal is the use of **recursion**. The method needs to do only three things:
 - 1. call itself to traverse the node's left subtree.
 - 2. visit the node .
 - 3. call itself to traverse the node's right subtree.
- **Preorder and postorder traversals:**
 - These traversal are useful if you are writing programs that parse or analyze **Algebric expression.**

public void traverse(int traverseType)

```
switch(traverseType)
```

```
swiich(i
```

```
case 1: System.out.print("\nPreorder traversal: ");
preOrder(root);
```

break;

```
case 2: System.out.print("\nInorder traversal: ");
inOrder(root);
```

break;

```
case 3: System.out.print("\nPostorder traversal: ");
postOrder(root);
```

break;

```
System.out.println();
```

Binary Search Trees private void preOrder(element localRoot)

```
if(localRoot != null)
```

System.out.print(localRoot.iData + " "); preOrder(localRoot.leftChild); preOrder(localRoot.rightChild);

Binary Search Trees private void inOrder(element localRoot)

```
if(localRoot != null)
```

inOrder(localRoot.leftChild); System.out.print(localRoot.iData + " "); inOrder(localRoot.rightChild);

Binary Search Trees private void postOrder(element localRoot)

```
if(localRoot != null)
```

```
postOrder(localRoot.leftChild);
postOrder(localRoot.rightChild);
System.out.print(localRoot.iData + " ");
```

Complete Java program for Tree^{5 August, 2010}

Binary Search Trees

class element

int idno;

String stname; element leftchild; element rightchild;

class binaryTree {
 public element root;
 public void insert(int id, String name)

```
element newstudent = new element ();
newstudent.idno= id;
newstudent.stname = name;
if(root == null)
  root = newstudent;
else
{
    element current = root;
```

```
element parent;
```

Binary Search Trees while(true) public void displayTree() { parent = current; inOrder(root); and Algorithms if(id < current.idno) current = current.leftchild; public void inOrder(element if(current == null)localRoot) { parent.leftchild = newstudent; if(localRoot != null) { return; Structures inOrder(localRoot.leftchild); else System.out.print(localRoot.idno current = current.rightchild; 11 "); +if(current == null)Data inOrder(localRoot.rightchild); parent.rightchild = newstudent; return; By: Sayed Hassan Adelyar

class binaryTreeApp { public static void main(String [] args) { binaryTree tree1 = new binaryTree(); tree1.insert(80, "Sharif"); tree1.insert(30, "Shams"); tree1.insert(120, "Jalal"); tree1.insert(125, "Jamal"); tree1.insert(100, "Jawed"); tree1.insert(90, "Jamil"); tree1.insert(95, "Zabi"); tree1.insert(60, "Wali"); tree1.insert(20, "Khan"); tree1.insert(10, "Karim"); tree1.insert(45, "Sultan"); tree1.insert(40, "Zobair"); tree1.displayTree();

- The efficiency of Binary Trees:
- As you have seen, most operations with trees involve descending the tree from level to level to find a particular node. How long does it take to do this? In a full tree, about half the nodes are on the bottom level.
- Thus, about half of all searches or insertions or deletions require finding a node on the lowest level. An additional quarter of these operations require finding the node on the next-to-lowest level, & so on. During a search we need to visit one node on each level. So we can get a good idea how long it takes to carry out these operations by knowing how many levels there are:

	Binary Search Trees	
	Number of nodes	Number of levels
Structures and Algorithms	1	1
	3	2
	7	3
	15	4
	31	5
	1023 32767	10 15
	1048575	20
Data	33554432	25
	1073741824	30

This situation is very much like the ordered array. In that case the number of comparison for a binary search was approximately equal to the base 2 logarithm of the number of cells in the array. Thus, the time needed to carry out the common tree operations is proportional to the base 2 log of N.